

#### INTRODUCTION TO ROBOTICS

(Kinematics, Dynamics, and Design)

SESSION # 4:

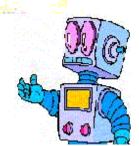
**APPLICATIONS OF ROBOTICS** 



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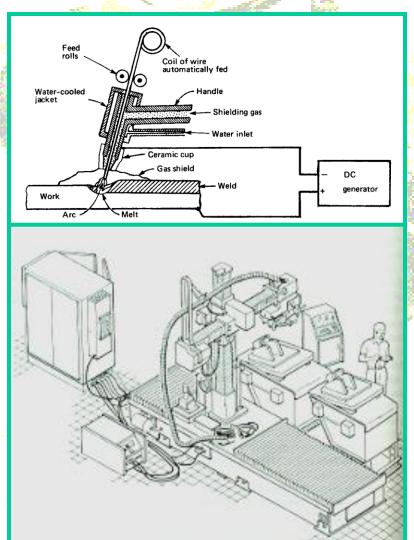


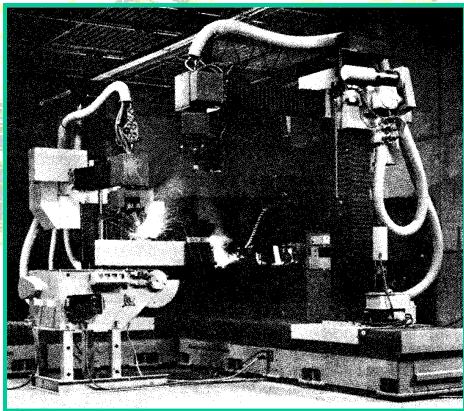
# Robotics in Automobile Industry (i.e Welding, Painting, Cutting, etc.)





#### An Automated Arc Welding Operation







# An Automated Auto Body Spot Welding Operation Line





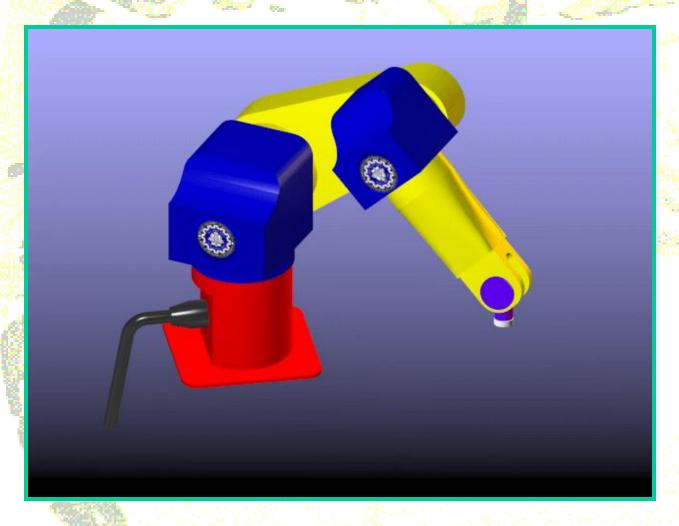


# An Automated TIG (Tungsten Inert Gas) Welding Operation





# A Glimpse of Robotic Applications in Automobile Industry





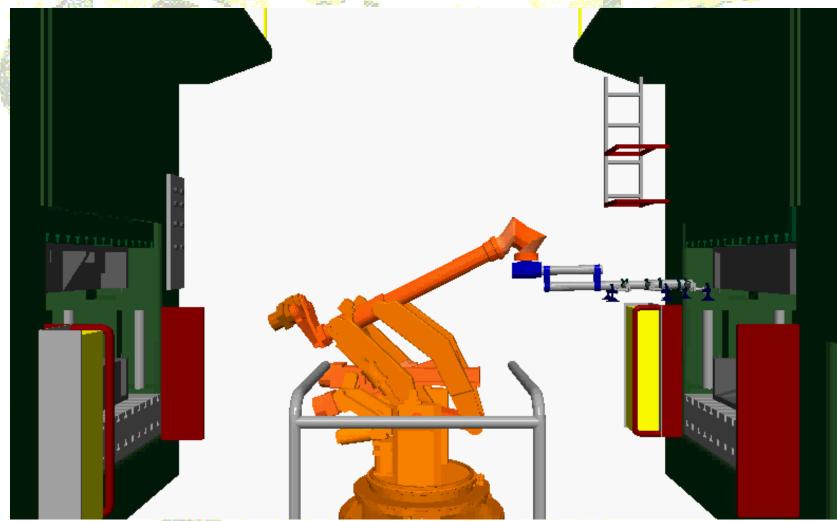
### **Advanced Manufacturing Research Center**







### A Robotic System Assisting a Press





# An Automated Steel/Brass Parts Polishing Operation

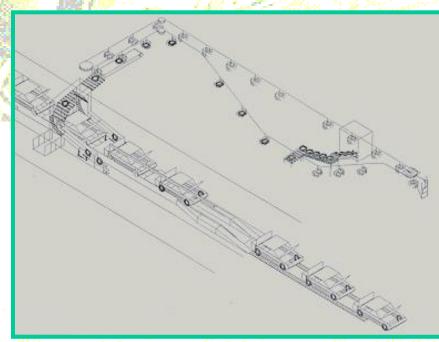






# **An Automated Vehicle Wheel Mounting Operation**







### A Fully Automated Cognitive Factory Equipped with an Automated Warehouse





# Robotics Applications in Food Industries

(i.e. Packaging, Sorting, Filling, and Cooking Operations, etc.)

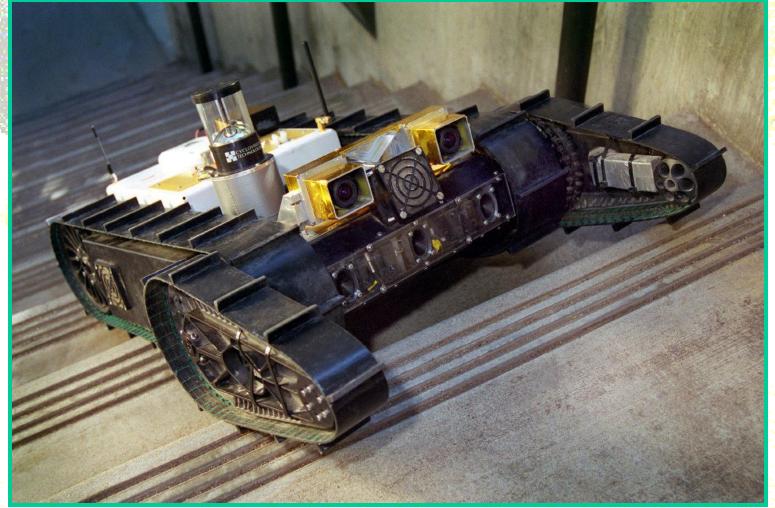


### A Robotic Arm Arranging Chocolates in Boxes





# Applications in Military & Defense Industries (i.e Combat Robots, etc.)





# Robots in Agricultur/Farms









### The Military Robots

(Surveillance Operations in Unstructured Environments)







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شبیهسازی و ساخت یک روبات کوهستان

Simulation and Fabrication of a Mountain Robot



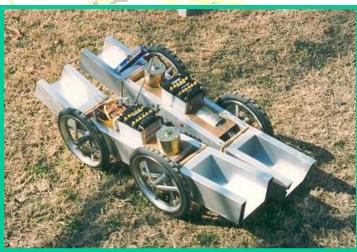
#### The Mountain-Terrain Robot

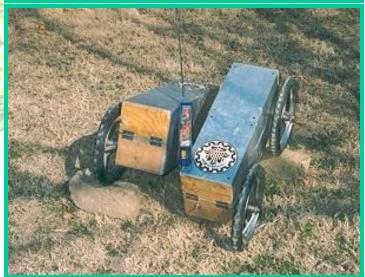
Mobile Robots/Manipulators (Meghdari-Nasiraei, 1995)

#### Advantages:

- Extended workspace.
- > Applicable to various environments.
- Ability to go over obstacles in rough terrain.







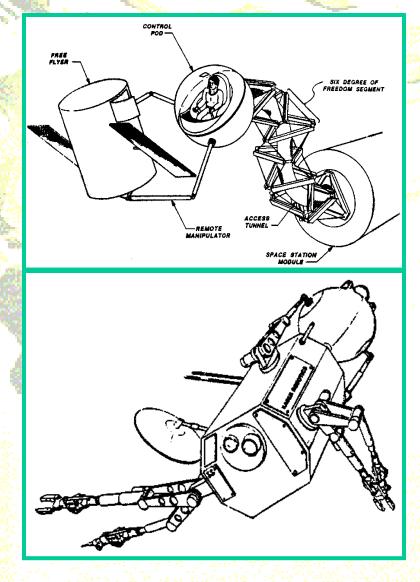


# Personal Occupied Woven Envelope Robot (POWER)

Consists of a huge flexible, hollow manipulator arm with numerous actuators. The operator rides in control cabin at the free end of the arm.

# Kader Astrobot with Propulsion Unit

A state-of-the-art telerobot with remote manipulators of high dexterity for space exploration.



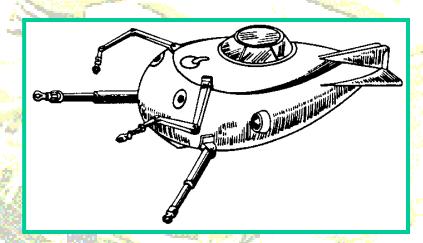


#### Information & Manipulation Underwater Robotics Systems

- Remotely Operated Vehicles (ROV)
- Robotic Underwater Vehicles (RUV)

#### They are applied for:

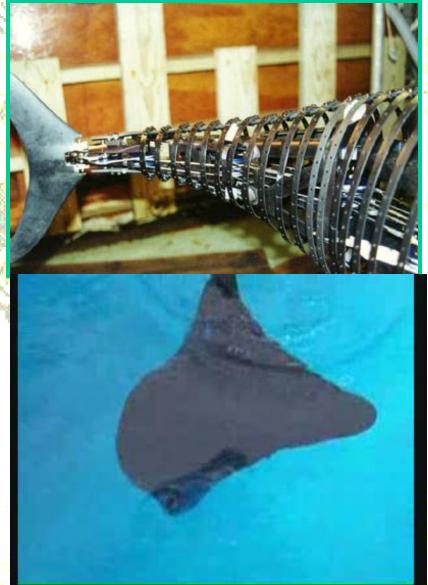
- work in ocean bottom to serve oil and gas installations.
- Exploration in other unconventional and hostile environments where human life is directly jeopardized (i.e. mine sweeping operations, spying operations, etc.)
- Exploration of marine plants and animals for medical purposes.



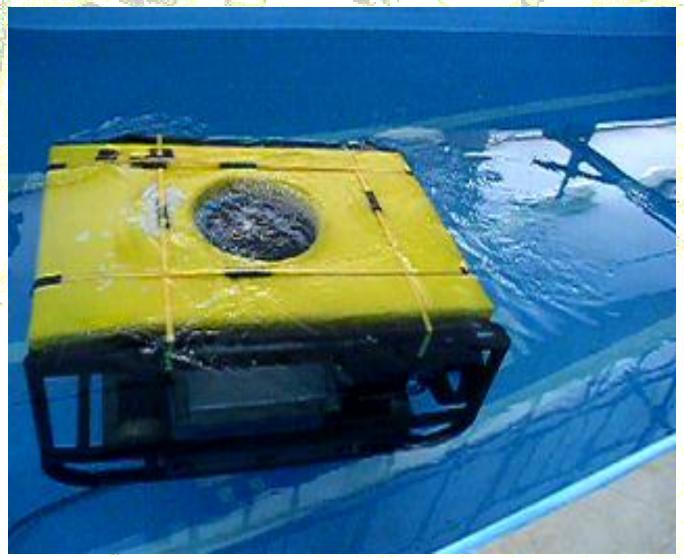


Searching and Surveillance Operations (i.e. searching for remains of a crashed airplane/black boxes)















SUT Campus-Kish Island, 2015.

# آبرُبات-Waterobot



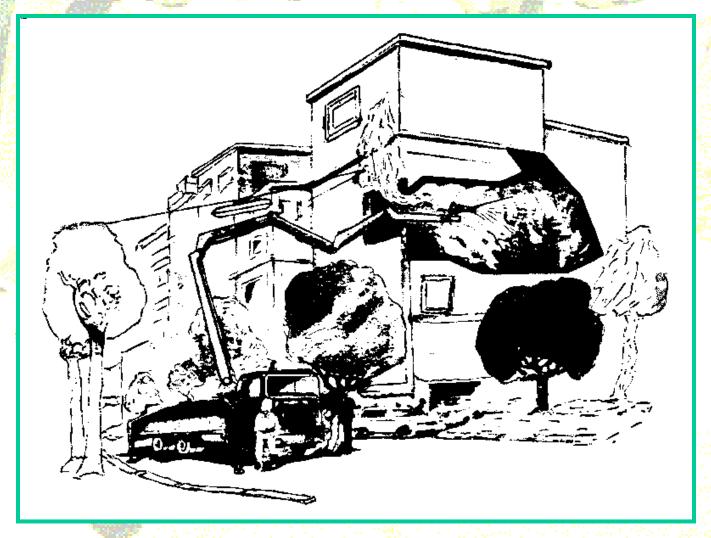






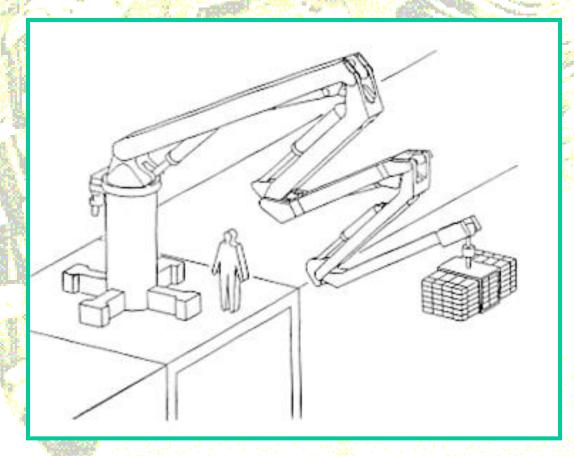


# Mobile Tele-Robotics Systems Assisting in Fire-Fighting



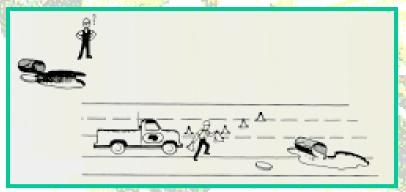


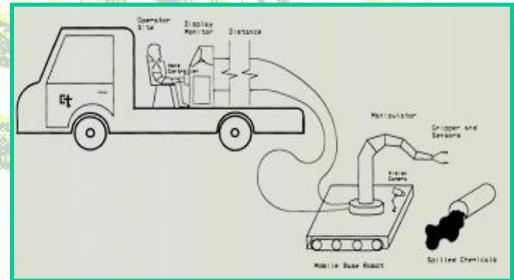
# Mobile Tele-Robotics Systems Assisting in Construction and Earthquake Clean-up



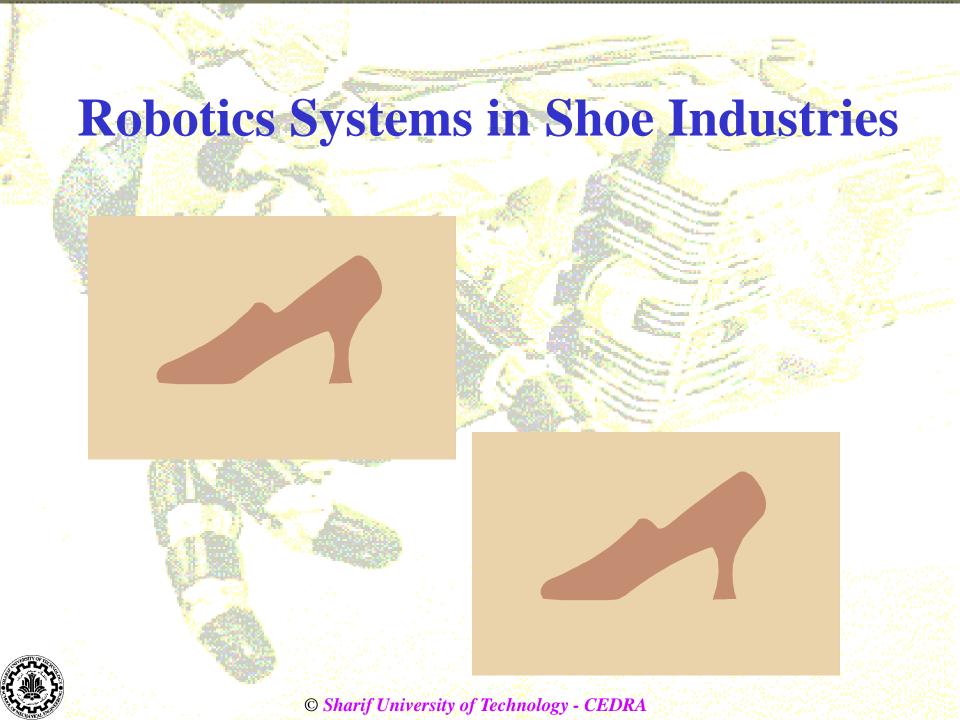


# Mobile Tele-Robotics Systems Assisting in Environmental Clean-up of Toxic Chemicals









# **Column Climbing Robot**

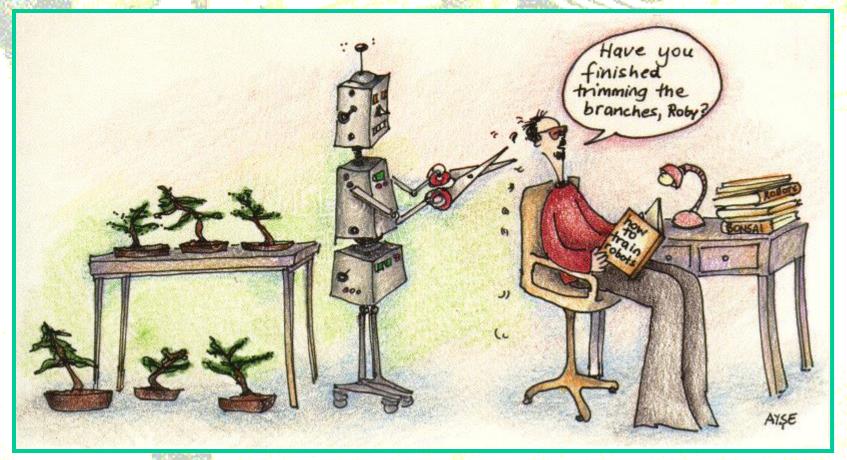






# Robotics Applications in Agriculture and Gardening

(i.e Cutting trees, Picking fruits, etc.)





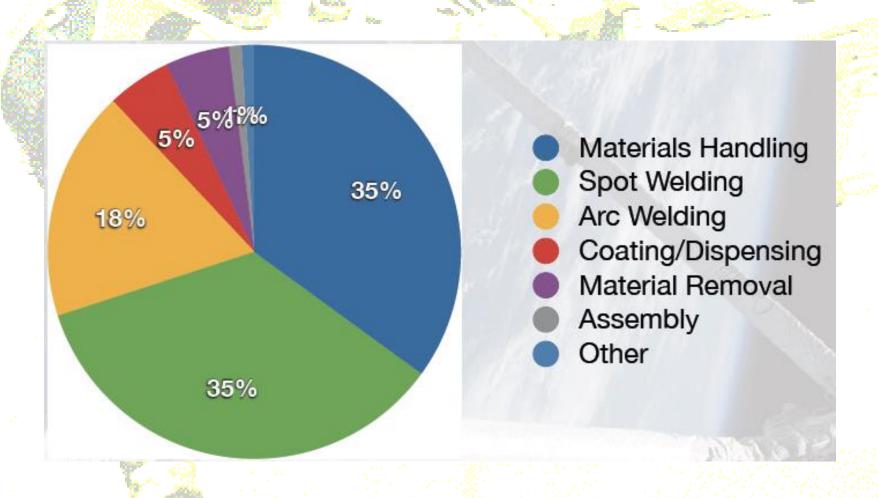
# Other Possible Applications of Robotics

- Barber Robots (Cut Hair)
- Cooking Robots
- Garbage Collector Robots
- Materials Handling
- Paint a Picture with a Brush
- Perform Surgeries
- Pick Fruits
- Play Sports (football, volleyball, etc.)

- Post Office(i.e. mailman)
- Pump Gasoline in Cars
- Security Robots
- Sheer Sheep
- Street Cleaner Robots
- Vacuum a Rug/Carpet
- Wait Tables in Restaurants
- Wash/Clean Airplanes
- Wash Windows



## **Industrial Robotic Applications (2005)**





#### Service Robotic Applications (2005)

